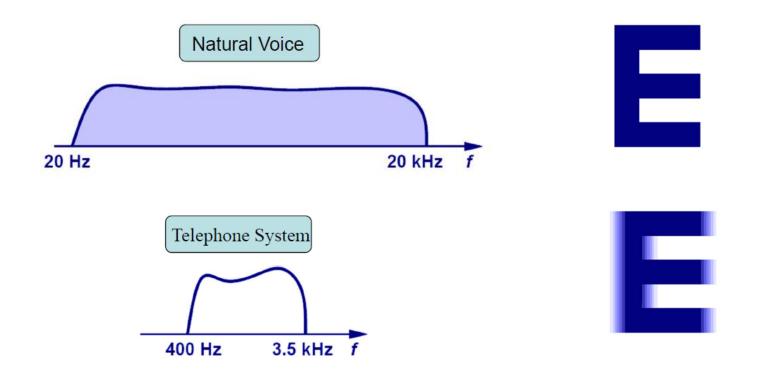






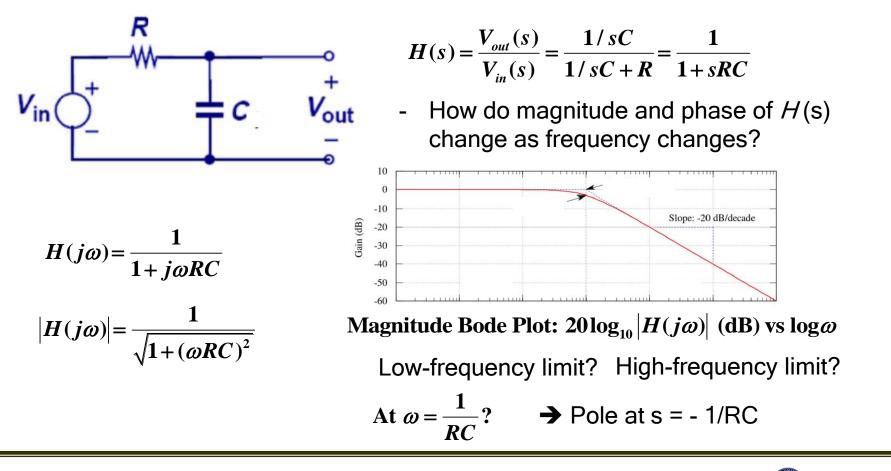
## Lect. 10: Pole, Zero, Bode Plot

- Examples of Frequency Roll-off



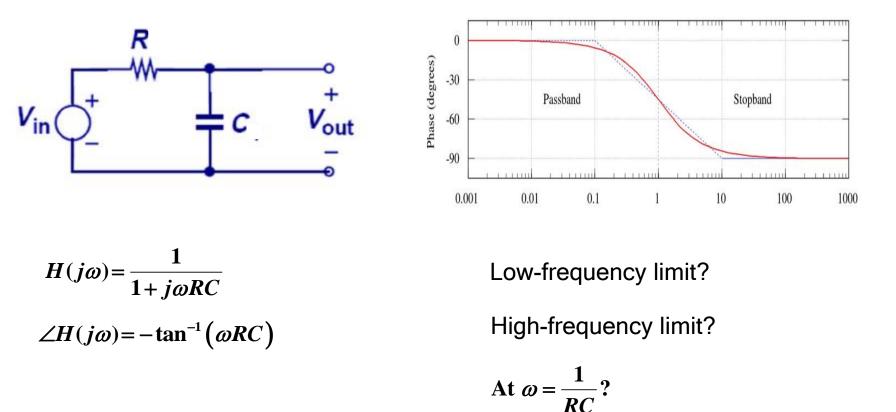


- How do we express frequency-domain characteristics of circuits?
- →Transfer functions in s-domain (Laplace Transform)



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- Phase Bode Plot (One-pole system)

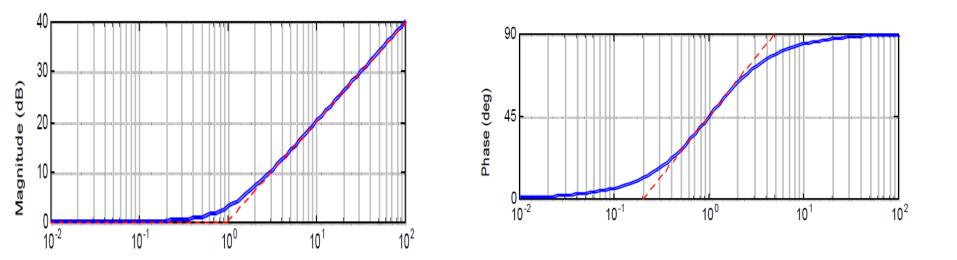




- How about H(s) = 1 + sRC?
  - $H(j\omega) = 1 + j\omega RC$

$$H(j\omega) = \sqrt{1 + (\omega RC)^2}$$

$$\angle H(j\omega) = \tan^{-1}(\omega RC)$$

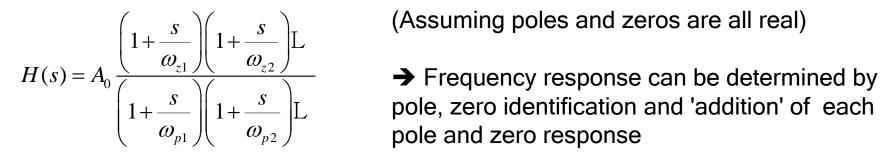




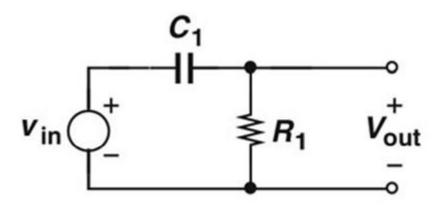


# Lect. 10: Pole, Zero, Bode Plot

In general, electronic circuits have multiple poles and zeros

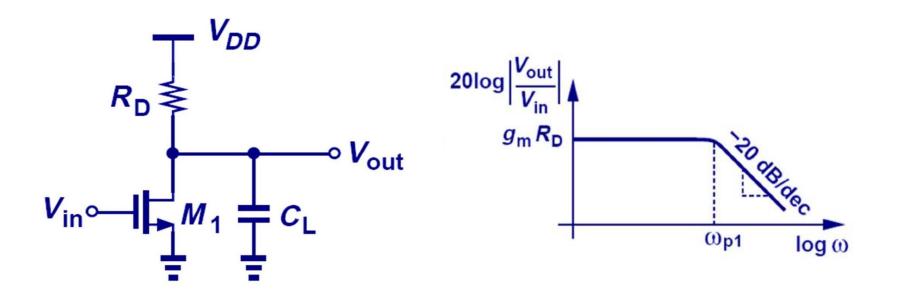


(Assuming poles and zeros are all real)



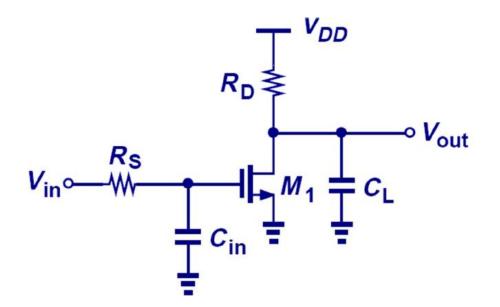


- Magnitude Bode Plot for MOS circuit (Ignoring MOS frequency response,  $\lambda = 0$ )



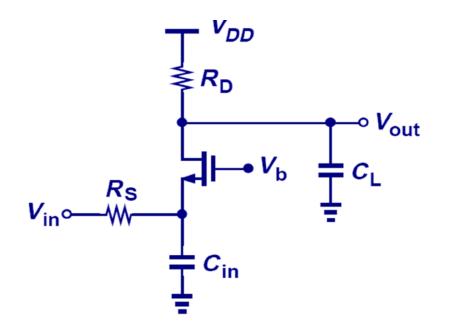


- Magnitude Bode Plot for MOS circuit (Ignoring MOS frequency response,  $\lambda = 0$ )





- Magnitude Bode Plot (Ignoring MOS frequency response,  $\lambda = 0$ )





- Homework: Determine magnitude Bode plot for V<sub>out</sub>/V<sub>in</sub> (Ignoring MOS frequency response,  $\lambda = 0$ . Assume input pole frequency is lower than output pole, zero frequency)

