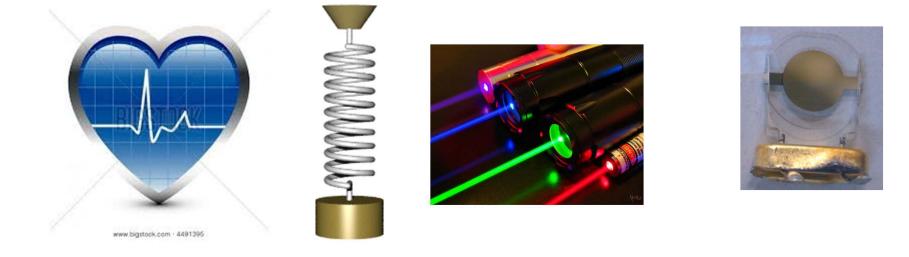
High-Speed Serial Interface Circuits and Systems

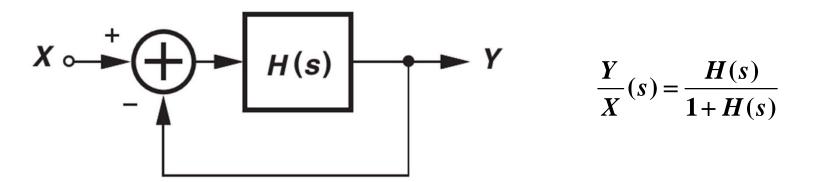
Lect. 2 – Ring Oscillators

Oscillator: A device undergoing periodic changes in certain physical quantities



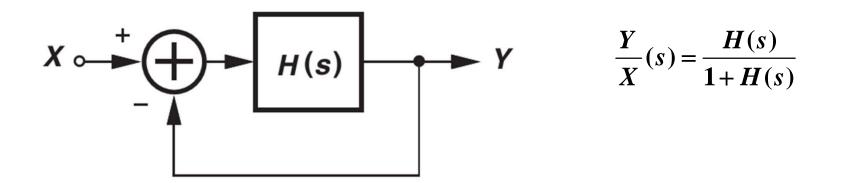
Our interests: MOS circuits that oscillate

Consider a negative feedback system



What happens when $H(j\omega) = -1$?

- ➔ Unstable
- → Output without input?
- \rightarrow Oscillation at ω



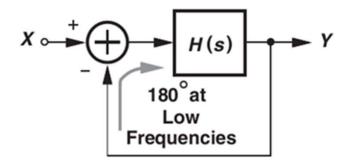
Barkhausen oscillation condition: $|H(j\omega)| = 1$ and $\angle H(j\omega) = 180^{\circ}$



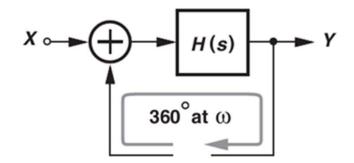
Heinrich Barkhausen (1881-1956)

German physicist / electrical engineer

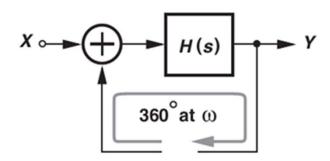
Invented first vacuum tube electronic oscillator in 1920



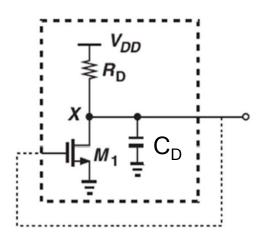
Barkhausen oscillation criterion: $|H(j\omega)| = 1$ and $\angle H(j\omega) = 180^{\circ}$



➔ in phase and same magnitude after one round trip



Oscillation: in phase and same magnitude after one round trip



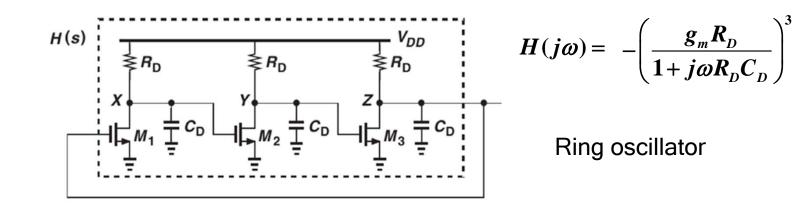
C_D represents all capacitive elements

Oscillation?

V_{DD}

Oscillation?

H(s)



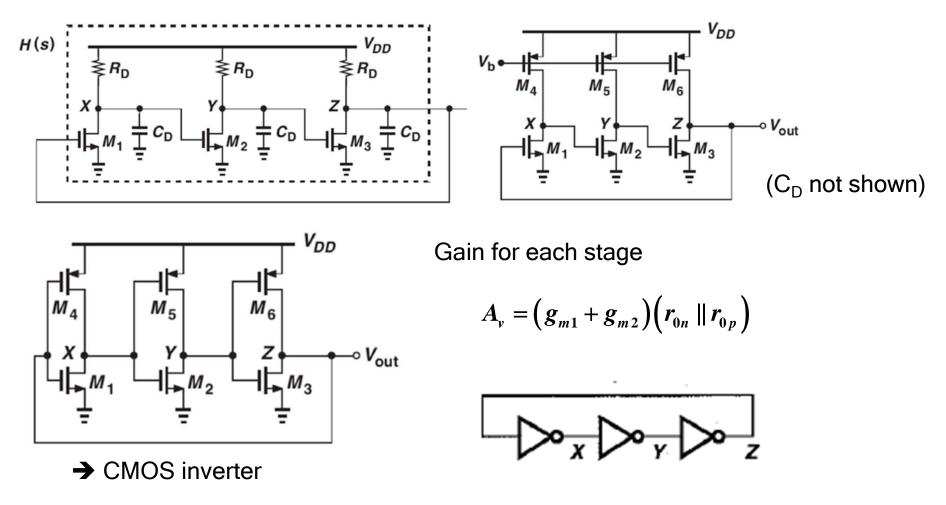
$$\angle \left(\frac{g_m R_D}{1 + j \omega R_D C_D}\right)^3 = -\pi$$

$$|H(j\omega)|^3 = 1$$

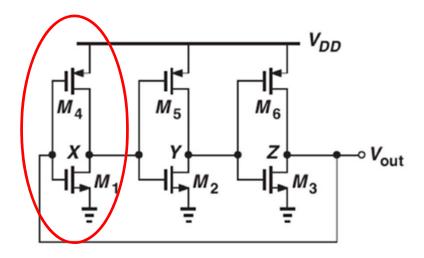
$$-3\tan^{-1}(\omega R_D C_D) = -\pi$$
$$\omega R_D C_D = \tan(\frac{\pi}{3}) = \sqrt{3}$$
$$\therefore \omega = \frac{\sqrt{3}}{R_D C_D}$$

$$|H(j\omega)|^{2} = \frac{(g_{m}R_{D})^{2}}{1+(\omega R_{D}C_{D})^{2}} = \frac{(g_{m}R_{D})^{2}}{1+3} = 1$$

$$\therefore g_m R_D = 2$$

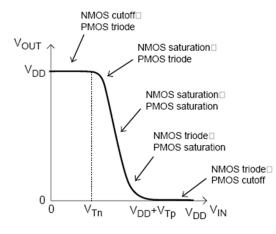


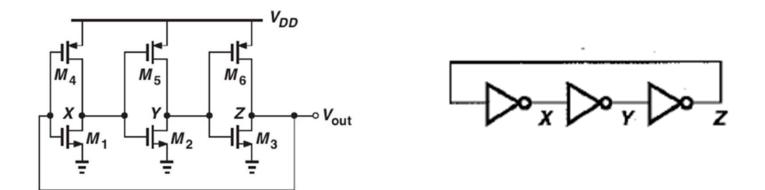
Without any input, what initiates oscillation?



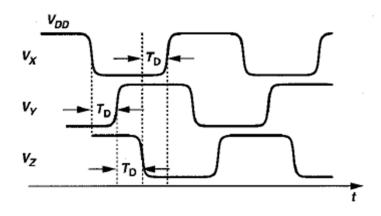
How large is the oscillation?

→ Large signal analysis





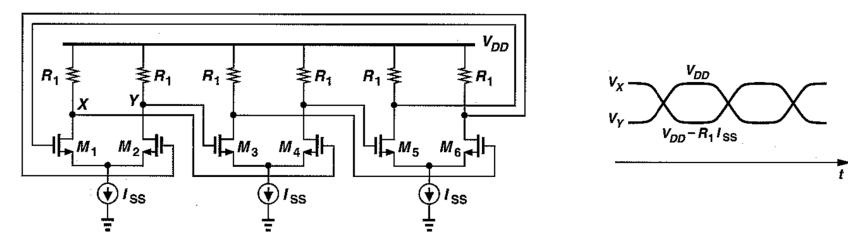
Oscillation frequency with large-signal analysis?



$$f_{osc} = 1 / (2 \times N \times T_D)$$

Requirement for N ?

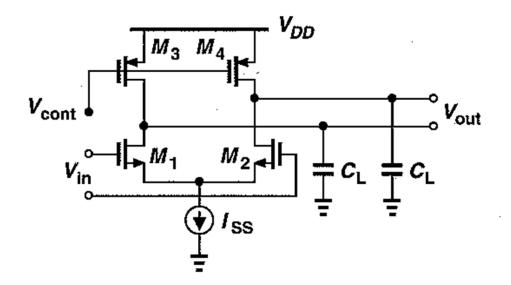
Differential amplifier for ring oscillator



Can be faster than CMOS inverter chain but consumes more power

Even-number stage possible

How can we control oscillation frequency with voltages? (Voltage-Controlled Oscillator: VCO)



→ Design Exercise