# High-Speed Serial Interface Circuits and Systems

Lect. 3 – LC Oscillators

(From Chap. 6 and 7 of Razavi)

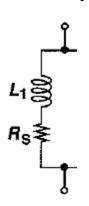
#### Inductors

- What is an inductor?
- How to make inductors?



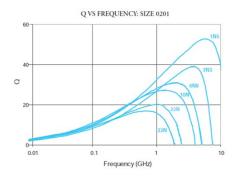
$$L = \frac{\mu N^2 A}{l}$$

- Non-ideality: Series resistance



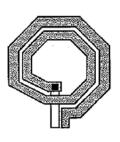
#### Rs:

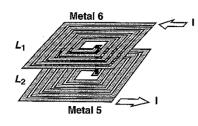
- Finite conductivity
- Skin effect: Surface currents induced by the magnetic field (eddy current) are concentrated near surface and effectively increases the resistance. More pronounced in higher frequency.
- Core loss: Dielectric loss
- Radiation loss
- Quality factor for an inductor:  $Q = \omega L/R$  (X/R)
- How does Q change with frequency?

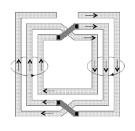


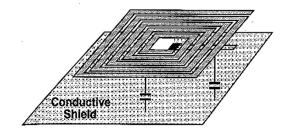
# **On-Chip Inductors**

- How to realize on-chip inductors?



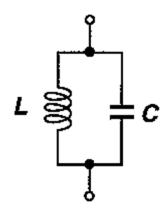






- On-chip inductors are typically lossy and large
- Recently, on-chip inductors are widely used since the required inductance is becoming smaller and processing technology is getting better

#### LC Tank



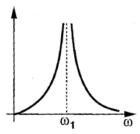
In s-domain

$$Z(s) = sL \| \frac{1}{sC} = \frac{sL}{s^2LC + 1}$$

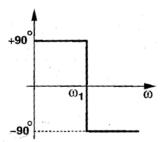
Poles at 
$$s = \pm j \frac{1}{\sqrt{LC}}$$

In steady-state 
$$s = j\omega$$
  $Z(j\omega) = \frac{j\omega L}{1 - \omega^2 LC}$ 

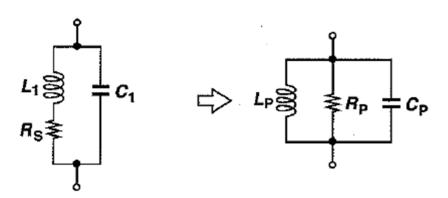
$$|Z(j\omega)| = \frac{\omega L}{|1-\omega^2 LC|}$$
  $\angle Z(j\omega) = \frac{\pi}{2} \text{ or } -\frac{\pi}{2}$ 



$$\angle Z(j\omega) = \frac{\pi}{2} \text{ or } -\frac{\pi}{2}$$

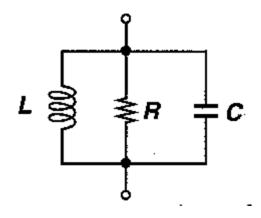


#### **RLC**



$$\begin{split} &C_p = C_1 \qquad R_s + L_1 s = R_p L_p s \, / \, (R_p + L_p s) \\ &L_P = L_1 (1 + \frac{R_S^2}{L_1^2 \omega^2}) \\ &\text{If Q } (= L_1 \omega / R_s) \text{ is large} \quad L_P \approx L_1 \\ &R_p \sim L_1^2 \omega^2 / R_s \sim Q^2 R_s \end{split}$$

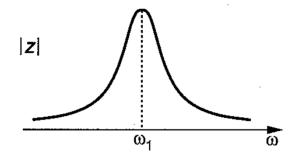
#### **RLC**

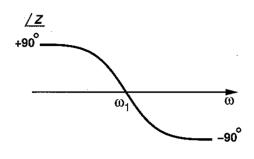


$$Z(s) = sL \| \frac{1}{sC} \| R \| = \frac{RLs}{RLCs^2 + Ls + R} = \frac{s/C}{s^2 + \frac{1}{RC}s + \frac{1}{LC}}$$

Poles at 
$$s = \frac{-\frac{1}{RC} \pm \sqrt{\left(\frac{1}{RC}\right)^2 - \frac{4}{LC}}}{2}$$

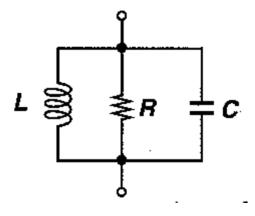
Two complex conjugate poles if 
$$\left(\frac{1}{RC}\right)^2 < \frac{4}{LC}$$
  $\rightarrow$  Under-damping

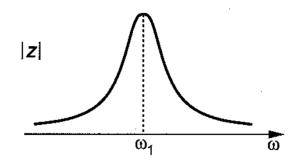




Magnitude peak and zero phase at  $\omega = \frac{1}{\sqrt{LC}}$ 

### **RLC**





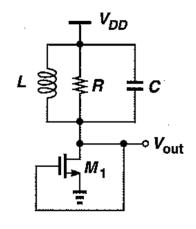
Q-factor:  $2\pi x$  (Energy Stored / Energy dissipated per cycle)

$$Q = R\sqrt{\frac{C}{L}}$$

For large Q, 3-dB bandwidth:  $\frac{1}{\sqrt{LCQ}}$ 

#### **LC** Oscillator

#### Oscillation?

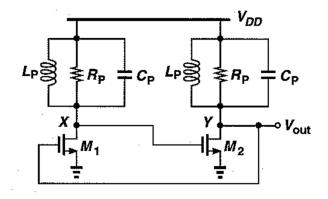


Assume M<sub>1</sub> has no capacitive component

At low frequency

At high frequency

At resonance frequency

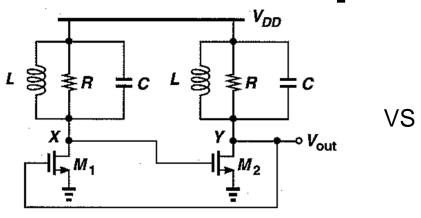


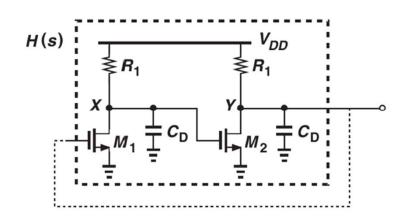
Oscillation!

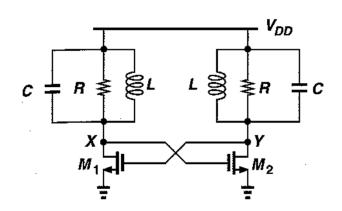
$$\omega = \frac{1}{\sqrt{LC}}$$

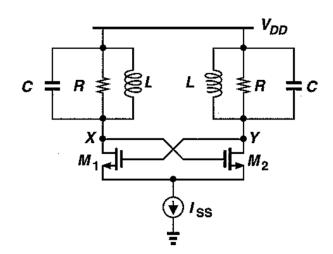
$$g_m R_p = 1$$

## **Cross-Coupled LC Oscillator**







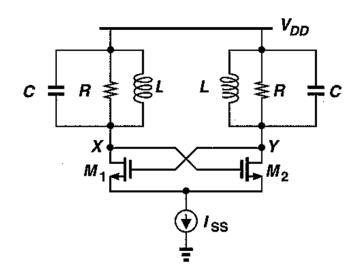


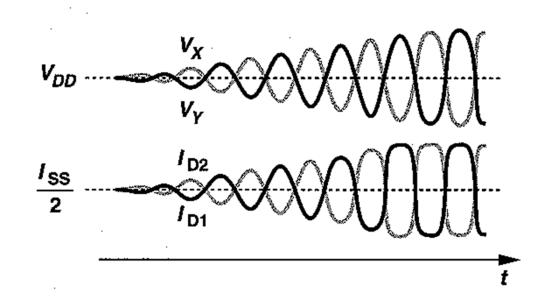
→ Cross-Coupled LC Oscillator

# **Cross-Coupled LC Oscillator**

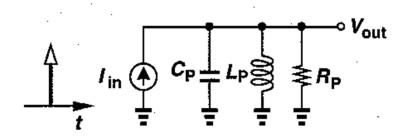
What initiates oscillation?

What limits oscillation?

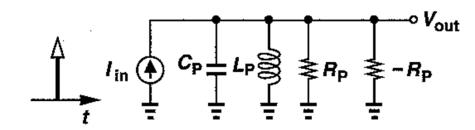




# **Negative G<sub>m</sub> Oscillator**

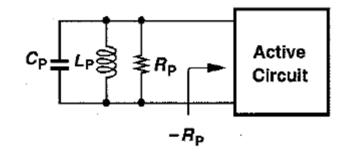






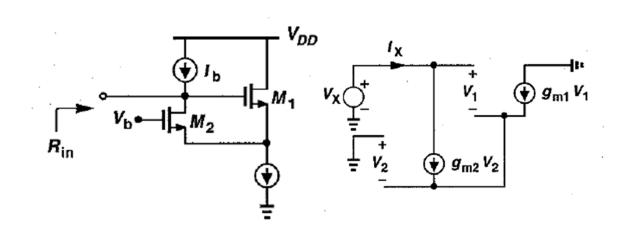


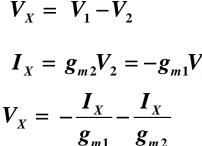
How do you make negative resistance circuit?



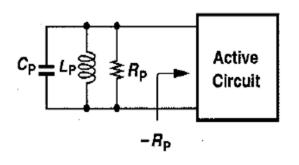
Active circuit with negative resistance in small signal

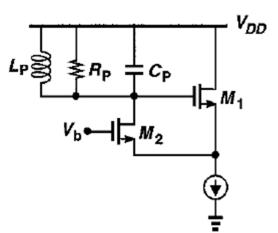
# **Negative Resistance Circuits**





$$R_{in} = \frac{V_X}{I_X} = -\frac{1}{g_{m1}} - \frac{1}{g_{m2}}$$





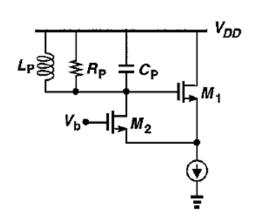
Negative G<sub>m</sub> oscillator

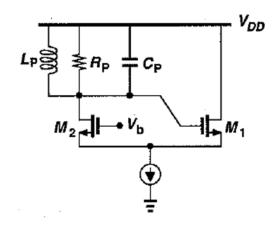
Oscillation frequency?

Oscillation condition?

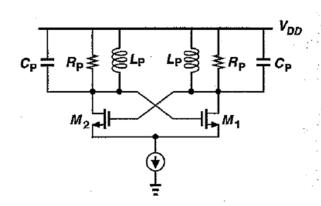
$$R_p = \frac{2}{g_m}$$

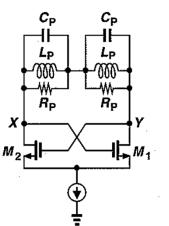
# **Negative-G<sub>m</sub> Oscillator**

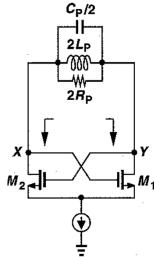




Differential Negative-G<sub>m</sub> Oscillator







$$R_{in} = -\frac{1}{g_{m1}} - \frac{1}{g_{m2}}$$

$$2R_p = \frac{2}{g_m}$$

$$g_m R_p = 1$$

Same configuration as cross-coupled LC oscillator

# **Negative-G<sub>m</sub> Oscillator**

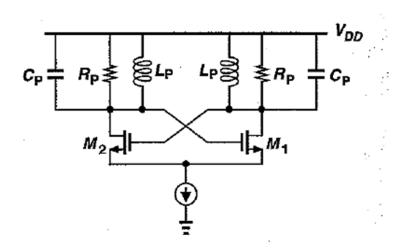
There many different types of oscillator circuits.

Sometimes your circuit oscillates when you do not want it. (unwanted feedback)

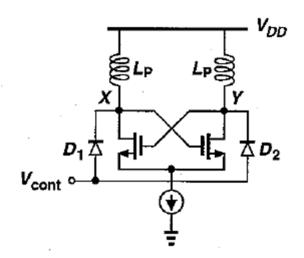
LC vs ring oscillators?

- LC provides cleaner oscillation (Smaller phase noise)
- RO is easier to implement for CMOS IC
- For very high-frequency applications, LC are used

### **Voltage-Controlled LC Oscillator**



Easiest to tune  $C_p$  with varactors

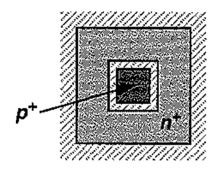


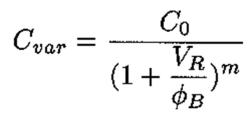
 $R_{\mbox{\tiny p}}$  is usually due to parasitic resistance for the inductor

#### **Varactors**

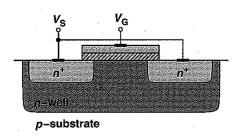
Reverse biased PN junction

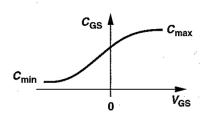






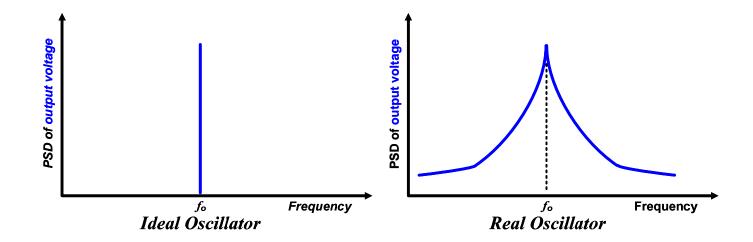
Tuning range is limited Very nonlinear



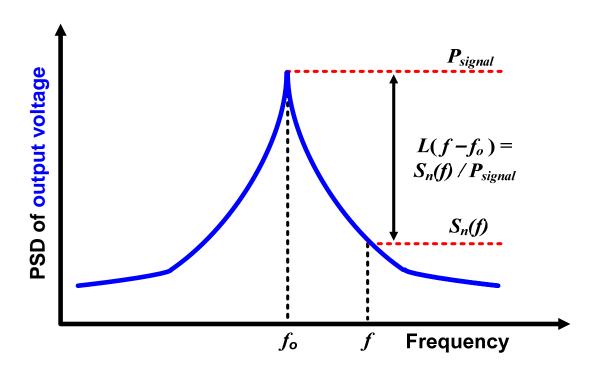


#### Phase Noise

• Ideal oscillator vs Real oscillator



#### Phase Noise



 Phase noise represented as single sideband noise (SSN) in log(dB) scale.

$$L(\omega) = 10\log \frac{S_n(\omega - \omega_o, \omega - \omega_o)}{P_{signal}(\omega_o)} (dBc / Hz) \sim \frac{4kT}{P_{dissipation}} \left(\frac{\omega_o}{2Q\omega}\right)^2$$

# **Design Exercise**

